

스테거드 페르미온을 사용한 K_{13} 붕괴 형태인자의 계산

측정 코드 테스트 방법 및 결과

배태길

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Cabibbo-Kobayashi-Maskawa Matrix Element, V_{us}

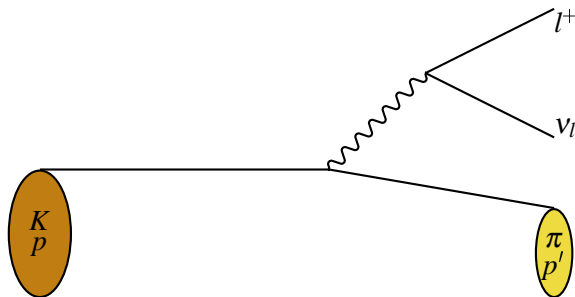
$$V_{\text{CKM}} = \begin{pmatrix} V_{ud} & V_{us} & V_{ub} \\ V_{cd} & V_{cs} & V_{cb} \\ V_{td} & V_{ts} & V_{tb} \end{pmatrix} \quad (1)$$

Unitarity on the first row

$$|V_{ud}|^2 + |V_{us}|^2 + |V_{ub}|^2 = 1 \quad (2)$$

- ▶ To test the unitarity, it is most important to determine V_{us} accurately since V_{ub} is negligibly small, and V_{ud} has been determined in high precision.
- ▶ Precise determination of V_{us} is also important in the Wolfenstein parameterization. (CP violation)
- ▶ $|V_{us}|$ is traditionally obtained from the experimental rate for K_{l3} decays.

K_{l3} Decay



The decay rate is expressed by

$$\Gamma(K_{l3}) = \frac{G_F^2}{192\pi^3} M_K^5 C^2 I |V_{us}|^2 |f_+(0)|^2 S_{\text{ew}} (1 + 2\Delta_{\text{SU}(2)} + 2\Delta_{\text{em}}). \quad (3)$$

$f_+(0)$ Vector form factor at zero momentum transfer,
 $q^2 = (p' - p)^2 = 0$

Form Factors

$$\langle \pi(p') | V_\mu | K(p) \rangle = C \{ (p_\mu + p'_\mu) f_+(q^2) + (p_\mu - p'_\mu) f_-(q^2) \} \quad (4)$$

$$f_0(q^2) = f_+(q^2) + \frac{q^2}{m_K^2 - m_\pi^2} f_-(q^2) \quad (5)$$

V_μ Vector current operator, $\bar{s}\gamma_\mu u$.

C Clebsche-Gordan coefficient, (1 for neutral kaon; $1/\sqrt{2}$ for charged kaon)

$f_0(q^2)$ Scalar form factor. By definition, $f_0(0) = f_+(0)$.

- ▶ In the SU(3) symmetry limit ($m_u = m_d = m_s$), $|f_+(0)| = 1$ and $f_-(0) = 0$.
- ▶ The deviation of $f_+(0)$ from unity is of order $(m_s - \hat{m})^2$ by the Ademollo-Gatto theorem. ($\hat{m} = (m_u + m_d)/2$)

Lattice QCD

Euclidean Path Integral

$$\begin{aligned}\langle \mathcal{O} \rangle &= \frac{1}{Z} \int \mathcal{D}[U] \mathcal{D}[\bar{\psi}] \mathcal{D}[\psi] \mathcal{O}[U, \psi, \bar{\psi}] e^{-S_G[U] - S_F[U, \psi, \bar{\psi}]} \\ &= \frac{1}{Z} \int \mathcal{D}[U] e^{-S_{\text{eff}}[U]} A[U] \sum_{z_1 \cdots z_n} \boldsymbol{\epsilon}_{y_1 y_2 \cdots y_n}^{z_1 z_2 \cdots z_n} M[U]_{z_1 x_1}^{-1} M[U]_{z_2 x_2}^{-1} \cdots M[U]_{z_n x_n}^{-1}\end{aligned}$$

$$S_F = \bar{\psi} M[U] \psi \quad (6)$$

$$\mathcal{O}[U, \psi, \bar{\psi}] = \psi_{y_1} \bar{\psi}_{x_1} \psi_{y_2} \bar{\psi}_{x_2} \cdots \psi_{y_n} \bar{\psi}_{x_n} A[U] \quad (7)$$

$$S_{\text{eff}} = S_G[U] - \ln \det M[U] = S_G[U] - \text{Tr} \ln M[U] \quad (8)$$

$$\langle \mathcal{O} \rangle = \lim_{T \rightarrow \infty} \frac{1}{Z_T} \text{Tr} \left[e^{-\hat{H}T} \mathcal{O} \right], \quad (9)$$

where $Z_T = \text{Tr}[e^{-\hat{H}T}]$.

Staggered Fermions

Staggered Fermion Action

$$S_F = a^4 \sum_n \left\{ \sum_\mu \frac{1}{2a} \eta_\mu(n) [\bar{\chi}(n) U_\mu(n) \chi(n + \hat{\mu}) - \bar{\chi}(n + \hat{\mu}) U_\mu^\dagger(n) \chi(n)] + m \bar{\chi}(n) \chi(n) \right\}, \quad (10)$$

where $\eta_\mu(n) = (-1)^{\sum_{\nu < \mu} n_\nu}$.

- ▶ Requires relatively low computational cost. Thus, it can be numerically simulated at lighter quark masses.
- ▶ But, it has 4 species per flavor. These are called “taste”.
- ▶ Furthermore, there are taste symmetry breaking at finite lattice spacing.
- ▶ For unimproved staggered fermions, this taste symmetry breaking results in significant discretization effects.

Correlation Functions

The hadronic matrix elements are obtained from calculating the relevant correlation functions.

$$C_{\mu}^{PQ}(t_1, t_2; \mathbf{k}_1, \mathbf{k}_3) = \sum_{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3} \langle \mathcal{O}_Q(\mathbf{x}_1, t_1 + t_0) V_{\mu}(\mathbf{x}_2, t_2 + t_0) \mathcal{O}_P^{\dagger}(\mathbf{x}_3, t_0) \rangle$$
$$\times e^{i\mathbf{k}_1 \cdot \mathbf{x}_1} e^{i(\mathbf{k}_3 - \mathbf{k}_1) \cdot \mathbf{x}_2} e^{-i\mathbf{k}_3 \cdot \mathbf{x}_3}$$
$$\xrightarrow{t_2, (t_1 - t_2) \rightarrow \infty} V_s \frac{Z_P^* Z_Q}{4E_Q(\mathbf{k}_1) E_P(\mathbf{k}_3)} \langle Q(\mathbf{k}_1) | V_{\mu} | P(\mathbf{k}_3) \rangle$$
$$\times e^{-E_Q(\mathbf{k}_1)(t_1 - t_2)} e^{-E_P(\mathbf{k}_3)t_2}. \quad (11)$$

$$C^P(t; \mathbf{k}_1) = \sum_{\mathbf{x}_1, \mathbf{x}_2} \langle \mathcal{O}_P(\mathbf{x}_1, t + t_0) \mathcal{O}_P^{\dagger}(\mathbf{x}_2, t_0) \rangle e^{i\mathbf{k}_1 \cdot (\mathbf{x}_1 - \mathbf{x}_2)}$$
$$\xrightarrow{t \rightarrow \infty} V_s \frac{Z_P^* Z_P}{2E_P(\mathbf{k}_1)} e^{-E_P(\mathbf{k}_1)t} \quad (12)$$

P and Q are either kaon or pion.

Interpolating Operators

In these calculations of the correlation functions, we use the following interpolating operators with staggered fermion fields.

Pseudo-scalar Operator

$$P(t, \mathbf{k}) = \sum_n \varepsilon(n) \bar{\chi}(n) \chi(n) e^{i\mathbf{k} \cdot \mathbf{n}}, \quad \varepsilon(n) = (-1)^{\sum_\nu n_\nu} \quad (13)$$

Vector Current Operator

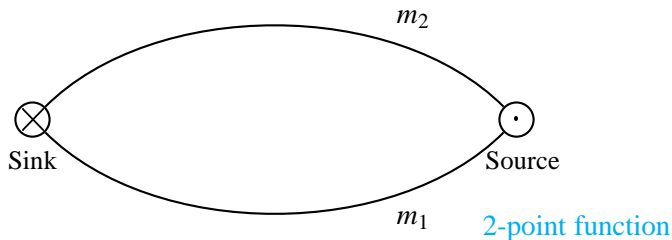
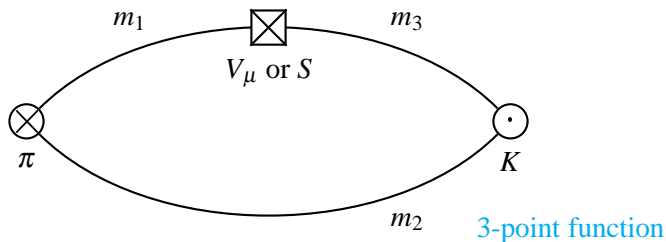
$$V_\mu(t, \mathbf{k}) = \frac{1}{2} \sum_n e^{i\mathbf{k} \cdot \mathbf{n}} \eta_\mu(n) [\bar{\chi}(n) U_\mu(n) \chi(n + \hat{\mu}) + \bar{\chi}(n + \hat{\mu}) U_\mu^\dagger(n) \chi(n)] \quad (14)$$

Scalar Operator

$$S(t, \mathbf{k}) = \sum_{n,c} \bar{\chi}^c(n) \chi^c(n) e^{i\mathbf{k} \cdot \mathbf{n}} \quad (15)$$

Diagrams of contractions of quark propagators

A correlation function is a contraction of quark propagators generated from sources.



Noise U(1) momentum sources and PxP insertion sources

To generate quark with non-zero momentum, we use Noise U(1) momentum sources. In the case of the 3-point functions, we need to insert $(\gamma_5 \otimes \gamma_5)$ operator into quark propagators and make new sources. These sources are called PxP insertion sources.

Noise U(1) momentum sources

$$h([\mathbf{n}, t], b; t'; p) = \delta_{t, t'} \eta(\mathbf{n}, b) e^{i\mathbf{p} \cdot \mathbf{n}} \quad (16)$$

PxP insertion sources

$$h_2(n, c; t_3; \mathbf{k}) = \delta_{t, t_3} \psi_2(n, c; t_1; \mathbf{0}) \varepsilon(n) e^{i\mathbf{k} \cdot \mathbf{n}}; \quad n = (\mathbf{n}, t) \quad (17)$$

The quark propagators are obtained by solving the Dirac equation with these sources.

$$\sum_{y, b} [\not{D} + m_f](x, a; y, b) \psi_f(y, b; t'; \mathbf{k}) = h(x, a; t'; \mathbf{k}) \quad (18)$$

Gauge Invariance Test

Under $SU(3)$ gauge transformation $g(x) \in SU(3)$,

$$U_\mu(x) \rightarrow g(x)U_\mu(x)g^\dagger(x + \hat{\mu}) \quad (19)$$

$$\psi(x) \rightarrow g(x)\psi(x) \quad (20)$$

Random $SU(3)$ gauge transformation over all lattice sites except for the $U(1)$ noise source time slice.

Random SU(3) matrix

Ref. : Maris Ozols, *How to generate a random unitary matrix.*

Random SU(2) matrices

$$SU(2) = \begin{pmatrix} e^{i\psi} \cos \phi & e^{i\chi} \sin \phi \\ -e^{-i\chi} \sin \phi & e^{-i\psi} \cos \phi \end{pmatrix} \quad (21)$$

Generate three random numbers: $\psi, \chi \in [0, 2\pi]$ and $\xi \in [0, 1]$

$\phi = \arcsin \sqrt{\xi} \rightarrow$ Uniformly distributed SU(2) matrices

Givens rotation $G(i, j)$: Rotate sub-matrix ((i, i), (i, j); (j, i), (j, j)) of 3x3 identity matrix by the generated random SU(2) matrix

$$G(i, j, \theta) = \begin{bmatrix} 1 & \cdots & 0 & \cdots & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & & \vdots & & \vdots \\ 0 & \cdots & c & \cdots & -s & \cdots & 0 \\ \vdots & & \vdots & \ddots & \vdots & & \vdots \\ 0 & \cdots & s & \cdots & c & \cdots & 0 \\ \vdots & & \vdots & & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & \cdots & 0 & \cdots & 1 \end{bmatrix}$$

Random SU(3) matrix = $G_1(1, 2)G_2(2, 3)G_3(3, 1)$

Ward Identity test

$$\partial_\mu V_\mu = (m_s - m_u)S \quad (22)$$

An Ward identity :

$$iq_\mu \langle \pi(p') | V_\mu | K(p) \rangle = (m_s - m_u) \langle \pi(p') | S | K(p) \rangle \quad (23)$$

Our correlation functions $C_\mu^{K\pi}(t, \mathbf{k})$ and $C_I^{K\pi}(t, \mathbf{k})$ correspond to the summations of $\langle \pi(k) | V_\mu | K(\mathbf{p} = \mathbf{0}) \rangle$ and $\langle \pi(k) | S | K(\mathbf{p} = \mathbf{0}) \rangle$ over whole space volume, respectively.

For $\mathbf{k} = 0$,

$$\partial_4 \langle \pi(0) | V^4 | K(\mathbf{p} = \mathbf{0}) \rangle = (m_s - m_u) \langle \pi(0) | S | K(0) \rangle. \quad (24)$$

We check that for $\mathbf{k} = 0$, $C_4^{K\pi}(t) - C_4^{K\pi}(t-1) = (m_s - m_u)C_I^{K\pi}(t)$.

Ward Identity test

```
1 $ ward_id.pl k2pi_ff.vector3p.t26t60.m0.00500.m0.01000.m0.05000.kx0ky0kz0.  
   k2pi_mu4.dat.30 k2pi_ff.scalar3p.t26t60.m0.00500.m0.01000.m0.05000.kx0ky0kz0  
   .k2pi_I.dat.30  
2 t1 = 26, t2 = 60  
3 ===== REAL PART =====  
4 t      C_4(t)-C_4(t-1) C_I(t)*(m_s-m_u) diff  
5 01 -1.3899336 -1.3899336 +4.024711e-11  
6 02 -1.1607124 -1.1607124 +2.260278e-10  
7 ....  
8 24 -0.034726026 -0.034726026 +2.061525e-11  
9 25 -0.028316772 -0.028316772 +3.851502e-10  
10 26 -0.17623825 -0.026272962 +8.509236e-01  
11 27 -0.023659762 -0.023659762 +1.104351e-10  
12 28 -0.02119814 -0.02119814 +5.400341e-11  
13 .....  
14 58 -2.2002058 -2.2002058 -1.610474e-10  
15 59 -1.9810066 -1.9810066 +2.122749e-10  
16 60 +28.494561 -2.5367882 +1.089027e+00  
17 61 -2.155153 -2.155153 +1.327788e-10  
18 ...
```

The disagreements in $t = 26$ and $t = 60$ are caused by the contact term.